

# Kritanu Chattopadhyay

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## EDUCATION

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### Delhi Public School Newtown

Class X – 97.8%

Kolkata, West Bengal

Apr 2021

### Haryana Vidya Mandir, Salt Lake

Class XII – 92.8%

Kolkata, West Bengal

Apr 2023

### National Institute of Technology, Durgapur

B.Tech in Mechanical Engineering, CGPA: 7.82

Durgapur, West Bengal

Aug 2023 – Present

## EXPERIENCE

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### AI-NLP Lab, IIT Patna

Undergraduate Research Intern, Department of Computer Science and Engineering

July 2025 – Present

Remote

- Undergraduate Research Intern under the supervision of *Professor Sriparna Saha*, guided by PhD Scholar Sofia Jamil.
- Summarizing Adverse Drug Events in Cancer Treatment using Large Language Models and Reinforcement Learning**
  - Developing an LLM and reinforcement learning-based system to summarize patient-reported adverse drug events in cancer treatment.
  - Designing NLP methods to process patient-reported data and generate concise, interpretable summaries for clinical decision-making.
  - Investigating scalable pipelines for continuous model improvement and integration into real-world healthcare settings.
  - Skills:** Natural Language Processing, Large Language Models, Reinforcement Learning, HuggingFace, PyTorch

### Autonomous Systems Laboratory, IIT Madras

Undergraduate Project Intern, Department of Engineering Design

May 2025 – July 2025

Chennai, Tamil Nadu, India

- Undergraduate Project Intern under the supervision of *Prof. Bijo Sebastian*, *Prof. Sandipan Bandyopadhyay*, and *Prof. G. Saravana Kumar*.
- Virtual Simulation of Dynamic Stability of Self-Propelled Boom Sprayer and Optimization of its CG for Different Load/Terrain Conditions**
  - Utilized **Altair MotionSolve** to develop and validate dynamic simulations for a company-sponsored project, analyzing stability under varying loads and terrains.
  - Simplified and optimized a CAD model with 10+ components, reducing computational load while maintaining accurate mass distribution.
  - Simulated cornering and slope tests of a 1.6-ton self-propelled boom sprayer, identifying critical speed ( $\approx 41$  km/h) and slope angle ( $\approx 30^\circ$ – $33^\circ$ ) for stability.
  - Delivered design insights on center of gravity placement and stability margins, informing safer and more reliable off-road agricultural vehicle design.
  - Skills:** CAD Simplification, Dynamic Simulation, Altair MotionSolve, Vehicle Dynamics, Virtual Prototyping

### Mechatronics Lab, IIT Delhi

Undergraduate Research Intern, Department of Mechanical Engineering

Feb 2025 – Present

Remote

- Undergraduate Research Intern under the supervision of *Professor Subir K. Saha*.
- Backend Development of RoboAnalyzer Robotics Analysis and Visualization Software**
  - Utilizing **Visual C#** to develop and enhance the backend of RoboAnalyzer, a robotics analysis and visualization software.
  - Implementing new features to improve simulation accuracy and system performance.
  - Debugging and optimizing existing modules to ensure scalability and reliability.
  - Collaborating with research mentors to align backend improvements with robotics research and use cases.
  - Skills:** Visual C#, Backend Development, Robotics Software, Debugging & Optimization

### CMATER Lab, Jadavpur University, Kolkata

Undergraduate Research Intern, Department of Computer Science and Engineering

Dec 2025 – Aug 2025

Remote

- Undergraduate Research Intern under the supervision of *Professor Debotosh Bhattacharjee*.
- SPAD Value Estimation from Rice Leaf Images**

- \* Formulated an ensemble approach combining CNN, DNN, XGBoost, and Random Forest with a linear regression meta-learner to predict chlorophyll (SPAD) values from rice leaf images.
- \* Trained and evaluated models on a Kaggle dataset of high-resolution rice leaf images with labeled SPAD values, applying preprocessing steps such as resizing, normalization, and RGB conversion.
- \* The ensemble model achieved an  $R^2$  score of 0.7820, outperforming individual models.
- \* Published results in a peer-reviewed paper accepted to **COMSYS 2025 (Warsaw, Poland)**, highlighting scalable non-invasive crop health monitoring.
- \* **Skills: Ensemble Learning, Deep Learning, Machine Learning, CNN, DNN, XGBoost, Random Forest, OpenCV, TensorFlow/Keras**
- **Cassava Leaf Disease Classifier**
  - \* Built a multi-backbone ensemble (ViT, ResNet-50, AlexNet, ConvNeXt, Swin-T) to classify 21,367 cassava leaf images across 5 disease categories.
  - \* Achieved 87.03% validation accuracy and 0.7733 macro F1-score, improving results by 2–8% over individual backbones.
  - \* Applied extensive data augmentation and ensemble soft voting to handle class imbalance and reduce overfitting.
  - \* Enabled scalable and automated disease detection to support precision agriculture and improve food security outcomes.
  - \* **Skills: Deep Learning, Transfer Learning, Vision Transformer, ConvNeXt, ResNet, Ensemble Learning, PyTorch**

## Robotics and Automation Laboratory, IIT Patna

Dec 2025 – Jan 2025

*Undergraduate Research Intern, Department of Mechanical Engineering*

*Bihta, Bihar, India*

- Undergraduate Research Intern under the supervision of *Professor Karali Patra*, guided by PhD Scholar Surya Prakash Singh.
- **Toolpath Generation for Texturing on Free-Form Surfaces**
  - \* Developed transformation matrices between two points on free-form surfaces, computing rotation angles and translational vectors for toolpath generation.
  - \* Implemented algorithms in **MATLAB** and **Python** for STL file rotation, point selection, and meshing-based coordinate extraction.
  - \* Created codes for selecting points on STL files using meshing and applying computed rotation/translation for accurate orientation.
  - \* Validated methodology on hemisphere and cube geometries, demonstrating accurate toolpath alignment and applicability to CNC machining.
  - \* **Skills: Computational Geometry, MATLAB, Python, Rotation and Translation Matrices, Euler Angles, 3D Meshing, CNC Toolpath Simulation**

## National Institute of Technology Durgapur

Jan 2025 – Present

*Undergraduate Research Intern*

*Durgapur, West Bengal, India*

- Undergraduate Research Intern under the supervision of multiple professors across the Department of Mechanical Engineering and the Department of Electrical Engineering.
- **Biped Robot Jumping Mechanism (with Professor Nirmal Baran Hui, Department of Mechanical Engineering)**
  - \* Designed walking and jumping control strategies for a biped robot using **MATLAB and Simulink**.
  - \* Developed simulation models for dynamic balance and ground reaction forces in collaboration with Mr. Debanuj Roy.
  - \* **Skills: MATLAB, Simulink, Biped Robotics, Dynamic Simulation**
- **Unmanned Aerial Vehicle Tracking Controller Design (with Professor Aritro Dey, Department of Electrical Engineering)**
  - \* Developing and implementing a tracking sliding mode controller for unmanned aerial vehicle dynamics using **MATLAB and Simulink**.
  - \* Simulating unmanned aerial vehicle trajectory tracking performance with robustness against external disturbances, in collaboration with Mr. Siddhartha Kundu.
  - \* **Skills: MATLAB, Simulink, Unmanned Aerial Vehicles, Nonlinear Control, Sliding Mode Control**
- **Eye Disease Classification with Deep and Transfer Learning (with Professor Soumya Chatterjee, Department of Electrical Engineering)**
  - \* Applied deep learning and transfer learning models (**DenseNet169, MaxViT-Tiny, EfficientNet-B0, ResNeXt-101, etc.**) for eye disease classification using **PyTorch**.
  - \* Achieved highest performance with DenseNet169, reaching **93.7% validation accuracy, 92.5% test accuracy, and 0.925 macro F1-score**, outperforming other models by 2–10%.
  - \* Benchmarked 13 state-of-the-art models on accuracy, precision, recall, and F1-score, highlighting DenseNet and ResNeXt as top-performing architectures.
  - \* **Skills: Deep Learning, Transfer Learning, DenseNet, EfficientNet, ResNeXt, PyTorch, Computer Vision, Medical Imaging**

## SKILLS

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**Soft Skills:** Communication, Community Outreach, Content Writing and Business Marketing.

**Programming Languages:** MATLAB, Python, C, Visual C#, SQL (mySQL), L<sup>A</sup>T<sub>E</sub>X.

**Hardware:** Arduino, ESP32

**Mathematics:** Linear Algebra, Statistics, and Calculus.

**Frameworks:** PyTorch, Tensorflow, Scikit-Learn, Mediapipe.

**Developer Tools:** VS Code, Visual Studio.

**Libraries:** Pandas, NumPy, Matplotlib, Seaborn, OpenCV, OpenTK, HelixToolkit3D, Streamlit

**Languages:** English (Fluent), Bengali (Native), Hindi (Fluent), German (Beginner).

**Simulation Softwares:** Ansys WorkBench, Simulink, Altair MotionSolve, Altair HyperMesh, Altair HyperGraph.

**CAD tools:** SolidWorks, Autodesk Fusion360, CATIA V5R19.

## ACHIEVEMENTS

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- Paper accepted for presentation at **COMSYS 2025 (Warsaw, Poland)** on SPAD estimation using ensemble learning under the supervision of Prof. Debotosh Bhattacharjee, CMATER Lab, Jadavpur University.

- Semi-Finalist in **Flipkart GRiD 6.0 - Robotics Track**.

- Ranked 7th among all the teams that participated in **Prodylitics 2024** organised by IIM Indore.

## EXTRA - CURRICULAR

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### Society of Automotive Engineers Collegiate Club

May 2025 - Present

*Senior Coordinator*

*On-site*

- Domain - Robotics, Machine Learning and Automobiles.
- Introduced the weekly F1 Magazine - **Through the Formula Lens** as a part of SAE.
- Organized the Aarohan as a member of **Team Aavishkar**.

### Mechanical Engineers' Student Association, NIT Durgapur

March 2025 - Present

*Senior Coordinator*

*On-site*

- Organised the **CADathon** - a hackathon aimed at promoting CAD designing through the institute.

### Innovation and Incubation Cell, NIT Durgapur

Feb 2025 - Present

*Student Volunteer*

*On-site*

- Actively involved in producing curated content for the website of IIC NIT Durgapur.
- Member of the official **Content Wing of IIC NIT Durgapur**.
- Team Member of **AI2Summit** Team and the **IIC Chronicles**.

### Team NDORS, NIT Durgapur

Jun 2025 - Present

*Senior Member*

*On-site*

- Member of the **BAJA SAE NIT Durgapur Team NDORS**.
- Involved in the **Computer Aided Engineering and Steering System team of Team NDORS**.

### Aerial Robotics Research Group, NIT Durgapur

Jun 2025 - Present

*Senior Member*

*On-site*

- Involved in the team **AI/ML, Microcontroller and CAD Design tracks**.

### NayePankh Foundation

Aug 2024

*Fundraising Intern*

*Remote*

- Raised INR 5001 for the cause of providing sustainable education to the underprivileged children.

### Rendezvous, IIT Delhi

Aug 2024 - September 2024

*Campus Ambassador*

*Remote*

- Promoted the fest and their sponsors within the institute.

### Earth5R

Aug 2024 - Dec 2024

*Content Writer*

*Remote*

- Wrote multiple articles promoting environmental awareness.

## INTERESTS

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**Artificial Intelligence** : Machine Learning, Deep Learning, Natural Language Processing, Large Language Models, Reinforcement Learning and Computer Vision and their applications in the Biomedical Domain.

**Robotics** : Medical Robotics and Industrial Robotics.